TA 1	•	
170	am	Δ.
Τ.4	am	•

**Enrolment No:** 



## UNIVERSITY OF PETROLEUM AND ENERGY STUDIES

**End Semester Examination, May 2021** 

**Course: Control system engineering** 

Program: B.tech ASE/AVE Course Code: ECEG 4007 Semester: VIII Time 03 hrs.

Max. Marks: 100

## **SECTION A**

- 1. Each Question will carry 5 Marks
- 2. Instruction: Complete the statement / Select the correct answer(s)

S. No.	Question	CO
Q 1	What will be the nature of time response if the roots of the characteristic equation	CO2
	are located on the s-plane imaginary axis?	COZ
	a) Oscillations	
	b) Damped oscillations	
	c) No oscillations	
	d) Under damped oscillations	
Q2	controller is handy to deal with steady state error.	
		CO3
		COS
Q3	Consider a system with transfer function $G(s) = s+6/Ks^2+s+6$ . Its damping ratio will be 0.5	
	when the values of k is:	CO <sub>2</sub>
	a) 2/6 b) 3	
	b) 3 c) 1/6	
	d) 6	
Q4	The output in response to a unit step input for a particular continuous control system is $c(t)$ =	
Q <del>+</del>	1-e <sup>-t</sup> . What is the delay time Td?	
	a) 0.36	004
	b) 0.18	CO <sub>2</sub>
	c) 0.693	
	d) 0.289	
Q5	For the system 2/s+1, the approximate time taken for a step response to reach 98% of its final	
₹º	value is:	
	a) 1s	CO1
	b) 2s	COI
	c) 4s	
	d) 8s	
Q6	are two practical examples of open loop and closed loop system respectively.	CO1
	SECTION B	

## **SECTION B**

- 1. Each question will carry 10 marks
- 2. Instruction: Write short / brief notes

Q 7	Dynamic behavior of control systems can be adequately judged and compared under application of standard test signals. Describe various standard test signals commonly used in control system design. Give time domain, s-domain, and graphical representation of the signals.	CO1
Q 8	Derive the transfer function $C(s)/R(s)$ for the given SFG using mason's gain formula $R(s) \bigcirc G_1(s) \bigcirc G_2(s) \bigcirc G_3(s) \bigcirc G_4(s) \bigcirc G_5(s) \bigcirc C(s)$ $V_4(s) \bigcirc V_3(s) \bigcirc V_2(s) \bigcirc V_1(s) \bigcirc C(s)$ $H_1(s) \bigcirc G_7(s) \bigcirc V_5(s)$ $H_4(s) \bigcirc G_7(s) \bigcirc G_7(s)$	CO3
Q 9	Derive the transfer function representation from the generalized state space model.	CO4
Q 10	The maximum overshoot and settling time for a control system whose overall transfer function is standard second order system are 10% and 4 second respectively. The input being a unit step function. Determine the value of $\zeta$ and $\omega_n$ in order to satisfy these requirements.	CO2
Q 11	Determine the value of K for the following equation such that the roots lie towards the left of line $s = -1$ in s-plane using Routh-hurwitz criterion. $s^3 + 3s^2 + 3s + K$	CO1
	Section C	
1. 2.	Each Question carries 20 Marks. Instruction: Write long answer.	
Q12	Sketch the root locus plot for the system when open loop transfer function is given by $G(s)H(s) = \frac{K}{s(s+4)(s^2+4s+13)};$ Also determine (i) The value of K such that system become marginally stable. (ii) Frequency value for sustain oscillation.	CO4
	OR A system is represented by the equations given below $ \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -4 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u; x(0) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}^T $ Determine the state transition matrix $\phi(t)$ .	